

**A time series processing tool to extract climate-driven interannual  
vegetation dynamics using Ensemble Empirical Mode Decomposition  
(EEMD)**

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**Abstract – Interannual changes of vegetation are crucial in understanding ecosystem dynamics under global change. However, there is no automated tool to extract these interannual changes from remote sensing time series. To fill this gap, the Ensemble Empirical Mode Decomposition (EEMD) framework was refined and implemented to decompose time series of Normalized Difference Vegetation Index (NDVI) and reconstruct their interannual components. The performance of EEMD-based interannual NDVI detection was assessed using simulated time series, and its sensitivity to model and data parameters was determined to provide a basis for remote sensing applications. The sensitivity analysis highlighted application limitations for time series with low interannual to annual amplitude ratios and high irregularity in timing of growing seasons, as these factors have the strongest effects on the overall performance. However, within these limitations, the detected interannual components correspond well to simulated input components with respect to timing of episodes and composition of time scales. The applicability on real world NDVI time series was demonstrated by mapping the coupling between precipitation variability, interannual vegetation changes, and the El Niño Southern Oscillation and Indian Ocean Dipole phenomena for ecoregions in East and Central Africa. In most areas where precipitation was found sensitive to oceanic forcing, the EEMD detected vegetation changes matched the predicted response, except in dense forest ecosystems.**

**Keywords:** Time series analysis, Vegetation monitoring, Interannual variability, Ensemble Empirical Mode Decomposition, NDVI, Longitudinal data

## 31    **1. Introduction**

32        Interannual changes in vegetation cover and productivity are key to understanding the impacts of  
33    global climate change on ecosystem dynamics (Hilker et al. 2014; Luo et al. 2011). Such year to year  
34    variations in vegetation status critically influence ecosystem services such as terrestrial carbon  
35    sequestration (Piao et al. 2011) and regulation of the hydrological cycle (Liu et al. 2008). However,  
36    the response of vegetation to climatic anomalies is often ambiguous (Brando et al. 2010), variable  
37    across ecosystems (Holmgren et al. 2013; Piao et al. 2014) and subject to critical transitions at  
38    tipping points (Hirota et al. 2011). Therefore its quantification requires dedicated monitoring tools.

39        Satellite remote sensing is an excellent tool to assess land ecosystem dynamics as it provides  
40    periodic, spatially explicit and consistent measurements of biophysical processes at the Earth's  
41    surface (Baynard 2013). It has become an established monitoring instrument in the fields of forestry  
42    (Achard et al. 2002), agriculture (Atzberger 2013) and plant ecology (Xie et al. 2008). Several  
43    vegetation indices and biophysical parameter products have been derived over the past 35 years from  
44    different satellite sensors, e.g., NOAA-AVHRR (Cracknell 2001), SPOT-VGT (Maisongrande et al.  
45    2004), MODIS (Huete et al. 2002) and PROBA-V (Dierckx et al. 2014). A key product in these  
46    datasets is the Normalized Difference Vegetation Index (NDVI) which highlights vegetation  
47    greenness and photosynthetic activity (Tucker and Sellers 1986). The combined data archives form a  
48    unique long term NDVI record which has been used in numerous studies dealing with the effects of  
49    climate variability on vegetation status in space and time (e.g., Fensholt et al. 2012; Guo et al. 2014).

50        This paper proposes and validates a framework for a tool to detect interannual NDVI  
51    fluctuations, by considering the ensemble of past efforts in remote sensing data processing and  
52    introducing promising advances from another domain of science, i.e., signal processing.

53        Early approaches accounted for interannual variability in time series *implicitly* without explicitly  
54    separating the interannual component. In pioneer works (Anyamba and Eastman 1996; Nicholson

55 and Farrar 1994; Richard and Pocard 1998), the forcing role of climate variability on NDVI was  
56 explored by spatial representations of the (lagged) correlation between mean monthly or annual  
57 NDVI values and corresponding aggregate rainfall values. This principle of lagged linear response  
58 was further explored in a simple linear regression approach (Camberlin et al. 2007; Zhou et al. 2009;  
59 Zhou et al. 2014a), whereas other authors (De Keersmaecker et al. 2015; Myneni et al. 1996; Plisnier  
60 et al. 2000) introduced the use of standardized anomalies from the average annual season as the key  
61 to reveal interannual variability. Brown *et al.* (2010) elaborated this notion of climatic forcing at  
62 multiple interannual time scales, supported by an increasing insight in the mechanisms and the  
63 effects of regional climate oscillations (Holmgren et al. 2001; Nicholson and Kim 1997; Williams  
64 and Hanan 2011).

65 Other tools have been developed to *explicitly* separate different time scale components in NDVI  
66 time series using techniques from the signal processing domain. Methods range from Fourier spectral  
67 analysis (Immerzeel et al. 2005; Lhermitte et al. 2008; Roerink et al. 2003) and wavelet analysis  
68 (Torrence and Compo 1998) to specific tools to detect, separate and model intra-annual variability,  
69 long term trends and abrupt changes from satellite image time series: TIMESAT (Jönsson and  
70 Eklundh 2002), BFAST (Verbesselt et al. 2010) and SPIRITS (Eerens et al. 2014).

71 Despite this wide range of tools, there is no quantitative method that focuses on interannual  
72 fluctuations, which we believe are crucial in understanding and predicting the response of  
73 ecosystems to an increasingly variable climate. For example, Fourier analysis methods generally  
74 focus on mapping the occurrence of annual unimodal or bimodal growing seasons to distinguish land  
75 use patterns (e.g., Lhermitte et al. 2011), while longer time scales are only represented as harmonic  
76 frequencies which are not variable over time. Wavelet analysis provides a more flexible technique to  
77 detect interannual components which are themselves variable over time, beyond the static and strictly  
78 harmonic Fourier framework. It has therefore been applied in numerous studies to identify  
79 interannual components in NDVI and climatic time series (Galford et al. 2008; Martínez and Gilabert

2009; Quiroz et al. 2011). Swinnen (2008) used wavelet coherency, a form of cross-spectral analysis (Torrence and Webster 1999) to systematically examine the climate-vegetation coupling over all occurring time scales in the time-frequency domain.

However, a generic tool to study interannual NDVI components must yield easily interpretable components in the time domain, so as to not impose constraints for further processing (e.g., co-analysis with climatic series), and to allow integrated use with other time series toolboxes. An answer to the need of breaking down an NDVI series into different time scale components while preserving the time domain flexibility of the wavelet approach is found in the Empirical Mode Decomposition (EMD) methodology, proposed and elaborated by Huang and colleagues in their key publication (Huang et al. 1998). The EMD algorithm (summarized in Section 2.2, and detailed in Appendix A) iteratively extracts the intrinsic time scales from the series, yielding a finite set of components with decreasing frequency and a residual trend component. EMD has been applied to climatic or biogeophysical time series to analyze climate variability in general (Coughlin and Tung 2005; Molla et al. 2011; Pegram et al. 2008), to model slow components in climate simulations (Brisson et al. 2015), to assess climatic effects on plant phenology (Guan 2014), to aid crop classification (Chen et al. 2011) and to remove the effect of platform orbital drifts in cross-sensor image time series (Pinzon et al. 2005).

EMD and its extension Ensemble Empirical Mode Decomposition (EEMD; Wu and Huang 2009) are straightforward as a decomposition algorithm, except for the procedure to sort ensembles of components lacking explicitness, which we tackle in this paper. However, processing EEMD components to robust indicators of interannual variability has not been addressed yet and faces a number of problems. First, the capability of assigning components to their underlying physical processes (e.g., noise, annual climatology) has been demonstrated *ad hoc* (Coughlin and Tung 2005), but has not been formalized to make it applicable for systematic processing of large spatiotemporal datasets. Second, distinguishing significant signal components from noise-induced components

critically determines the method's performance and the conclusions that can be drawn from its output. Significance tests for (E)EMD components exist but lack validation, which is a prerequisite for a generic processing tool.

The overall aim of this work is to introduce the EEMD technique in remotely sensed image processing applications, and to propose a framework for its implementation and validation. More specifically, the objectives of this paper are:

- To define a robust procedure based on EEMD to separate interannual components in remotely sensed NDVI time series from annual and noise components;
- To assess the performance of this procedure and its sensitivity to EEMD model parameters and characteristics of the input time series;
- To demonstrate its applicability in a case study over East and Central Africa.

Based on the hypothesis that climate variability is reflected in NDVI time series as relatively weak, irregular and slow fluctuations, we composed simulated time series containing annual, interannual and noise components. In this way, we set up a validation framework in which the interannual component detected after decomposition can be compared to the original input component. After this validation, we assess the representativeness of our simulations for real world situations by examining the detected interannual NDVI response to precipitation in East and Central Africa. In the areas where precipitation is sensitive to regional climate variability, a corresponding vegetation response is expected in ecosystems with limiting precipitation.

## **2. Data and methods**

A remotely sensed NDVI dataset spanning the 1981-2014 period and covering a wide range of climate types and ecosystems (East and Central Africa) along with series of historic climate indices were used to set up a framework to test and validate the envisaged tool for interannual component detection. We adopted the Ensemble Empirical Mode Decomposition (EEMD) to obtain a per-pixel

129 estimate of the constituent components of NDVI series. These estimates were used to simulate  
130 annual, interannual and noise components with controlled variation of their parameters. A set of  
131 mixtures of simulated components were decomposed using EEMD, and the interannual components  
132 were reconstructed by three distinct approaches. Measures of correspondence between the input and  
133 output interannual components were calculated to evaluate the performance and sensitivity to various  
134 EEMD model parameters, data characteristics and reconstruction methods. Finally, the validated  
135 method was applied on the original NDVI dataset and historic climate indices in a regional case  
136 study.

## 137 2.1. Data

### 138 2.1.1. Remote sensing datasets

139 The Normalized Difference Vegetation Index (NDVI) is defined as the normalized difference in  
140 surface reflectance (*Refl*) in the near-infrared (*NIR*) and red (*R*) wavebands of a sensor and is  
141 considered to be a proxy for vegetation greenness (Tucker and Sellers 1986).

$$142 \quad NDVI = (Refl_{NIR} - Refl_R) / (Refl_{NIR} + Refl_R) \quad (Eq.1)$$

143 Various efforts have been made to produce consistent long term NDVI records from sensor  
144 sequences, each with their particular merits and flaws (Tian et al. 2015). Within the setup of this  
145 paper, residual inconsistencies in the baseline dataset do not fundamentally affect the data  
146 simulations or the validation results produced from them. Therefore, this section is limited to a  
147 description of the underlying datasets whereas the implications of data inconsistencies are discussed  
148 at length in the discussion section of this paper.

149 NASA's Long Term Data Record (LTDR) contains the reprocessed daily global AVHRR  
150 imagery from subsequent NOAA platforms (1981-1999 in version 2; extended with 2001-2013 in  
151 version 4), at 0.05° resolution. The LTDR reprocessing aims to achieve data consistency through  
152 both improved radiometric calibration (Vermote and Kaufman 1995), corrections for orbital drift

153 effects (Nagol et al. 2014; Vermote et al. 2009) and atmospheric corrections with ancillary  
154 meteorological data (Pedelty et al. 2007).

155 The SPOT-VEGETATION (VGT) programme (1998-2014) delivered global NDVI images of 1  
156 km resolution as ten-daily maximum NDVI synthesis products as to minimize cloud effects present  
157 in daily recordings (Deronde et al. 2014). Residual clouded pixels typically cause sharp troughs in  
158 temporal NDVI profiles. These are detected and their values replaced by means of an NDVI  
159 interpolation algorithm (Eerens et al. 2014; Swets et al. 1999) to represent a more realistic smooth  
160 temporal NDVI profile.

161 One approach to obtain a long uninterrupted baseline dataset is to merge the VGT archive (1998-  
162 2014) with the first part of the LTDR archive (1981-1999). Both image datasets were resampled to a  
163 common systematic 20 km frame and subjected to the same synthesis and smoothing procedures to  
164 yield comparable NDVI series. Finally, cross-sensor calibration reduces the inconsistencies between  
165 NDVI from the AVHRR and VGT sensors caused by differences in sensor spectral responses  
166 (Trishchenko et al. 2002), native spatial resolutions (Tarnavsky et al. 2008), platform orbits and  
167 sensor geometries (Swinnen and Veroustraete 2008). Empirical cross-sensor calibration was  
168 achieved following the linear VGT-to-AVHRR correction model proposed by Steven et al. (2003).  
169 We re-estimated the correction equation from corresponding pixels in images from 1999, applying  
170 geometric mean regression (Ji and Gallo 2006).

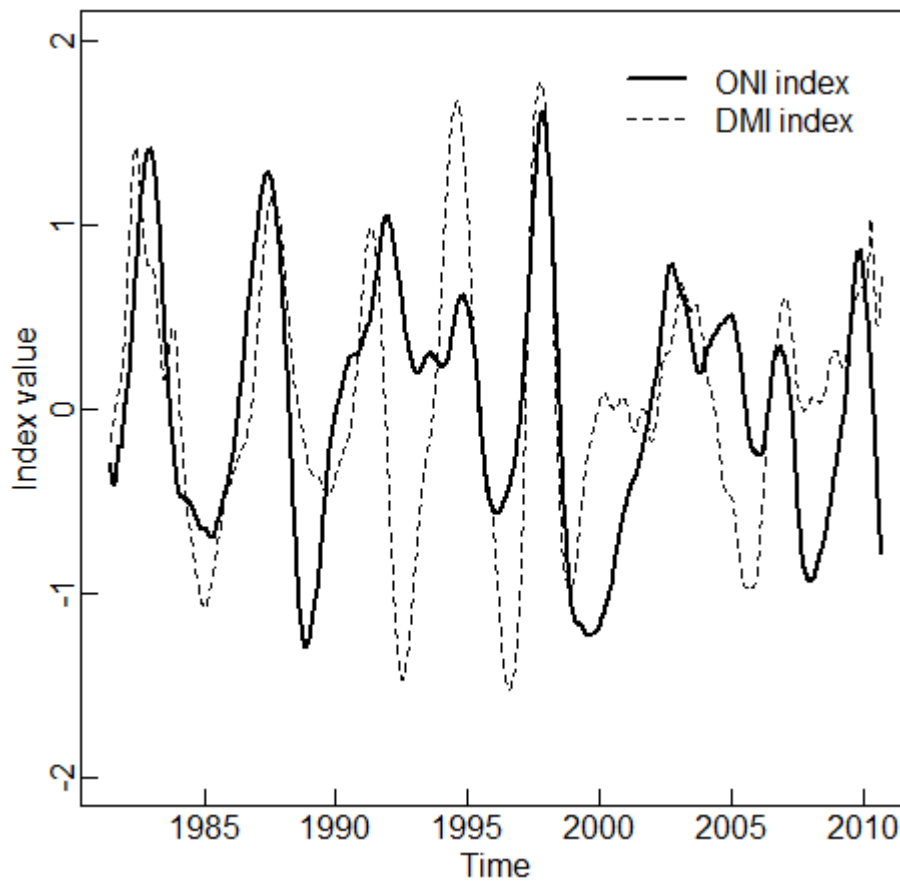
$$171 \quad NDVI_{AVHRR} = 0.799 NDVI_{VGT} + 0.081 \quad (RMSE = 0.069 NDVI) \quad (Eq.2)$$

#### 172 2.1.2. Climate data

173 Interannual climatic variability is represented in this study by two climatological indices which  
174 have been linked to interannual rainfall patterns in East and Central Africa (IPCC 2007). The  
175 Oceanic Niño Index (ONI) (NOAA-CPC 2014) represents sea surface temperature anomalies in the  
176 Pacific Ocean (ERSST v4; Huang et al. 2014) and is the most widely used indicator for the episodes



177 of the El Niño Southern Oscillation (ENSO), which are known to have impacts globally. In addition,  
 178 East Africa's rainfall is largely driven by the Indian Ocean dynamics, which as well display  
 179 interannual episodes as summarized in the Indian Dipole Mode Index (DMI) (JAMSTEC 2010). This  
 180 is the difference in sea surface temperature anomalies between the western and eastern equatorial  
 181 Indian Ocean. Monthly values for both indices were smoothed with a 12-month running window in  
 182 order to obtain an estimate of the interannual climatic forcing (Figure 1).



183  
 184 *Figure 1. The Oceanic Niño Index (ONI) and the Dipole Mode Index (DMI) are derived from sea*  
 185 *temperature measurements and represent the positive and negative episodes of climate oscillations*  
 186 *that affect interannual rainfall patterns over East and Central Africa (IPCC 2007).*

187 Gridded precipitation estimates derived from satellite observations (1983-2012) are obtained  
 188 from the PERSIANN system (Sorooshian et al. 2000). The PERSIANN system merges infrared

189 brightness images with rainfall estimates from satellite microwave data to daily 0.25° precipitation  
190 maps, with error detection and quality control using ground observations (Hsu et al. 1999).

## 191 2.2. Ensemble EMD decomposition model

192 For a detailed description of the basic EMD model, we refer to Huang *et al.* (1998), whereas the  
193 algorithmic implementation and its parameters are described in Appendix A. Briefly, EMD works by  
194 connecting local maxima (minima) in a series  $X(t)$  by a cubic spline which yields upper (lower)  
195 envelopes. The time series minus the mean of the upper and lower envelopes contains the high  
196 frequency information. In a process termed *sifting*, the above steps are repeated to remove residual  
197 low frequency information until the number of extrema and zero-crossings does not change for  $S$   
198 consecutive siftings. The outcome is a component of the original series that isolates a specific  
199 frequency of the series, termed an Intrinsic Mode Function (IMF). The residual of the data and a  
200 detected IMF is again subjected to the sifting process to iteratively yield a set of  $k$  IMFs ( $IMF_{i=1...k}$ )  
201 with decreasing frequency, until a final residual term  $R(t)$  has less than two local extrema.

$$202 \quad X(t) = \sum_i IMF_i(t) + R(t) \quad (\text{Eq.3})$$

203 Although powerful, basic EMD often leads to one time scale intermittently partitioned over two  
204 or more IMFs, an issue referred to as *mode mixing* (Huang et al. 1999), illustrated in Figure 2a. To  
205 cope with mode mixing, Wu and Huang (2009) proposed Ensemble EMD (EEMD) as an extension  
206 to the method. By iteratively adding a finite amount ( $\sigma_{\text{add}}$ ) of Gaussian white noise to the series,  
207 applying EMD to the mixture, grouping corresponding IMFs into ensembles, and averaging each  
208 ensemble of IMFs over a large number  $N_n$  of noise realizations, mode mixing is largely eliminated  
209 (Figure 2b).

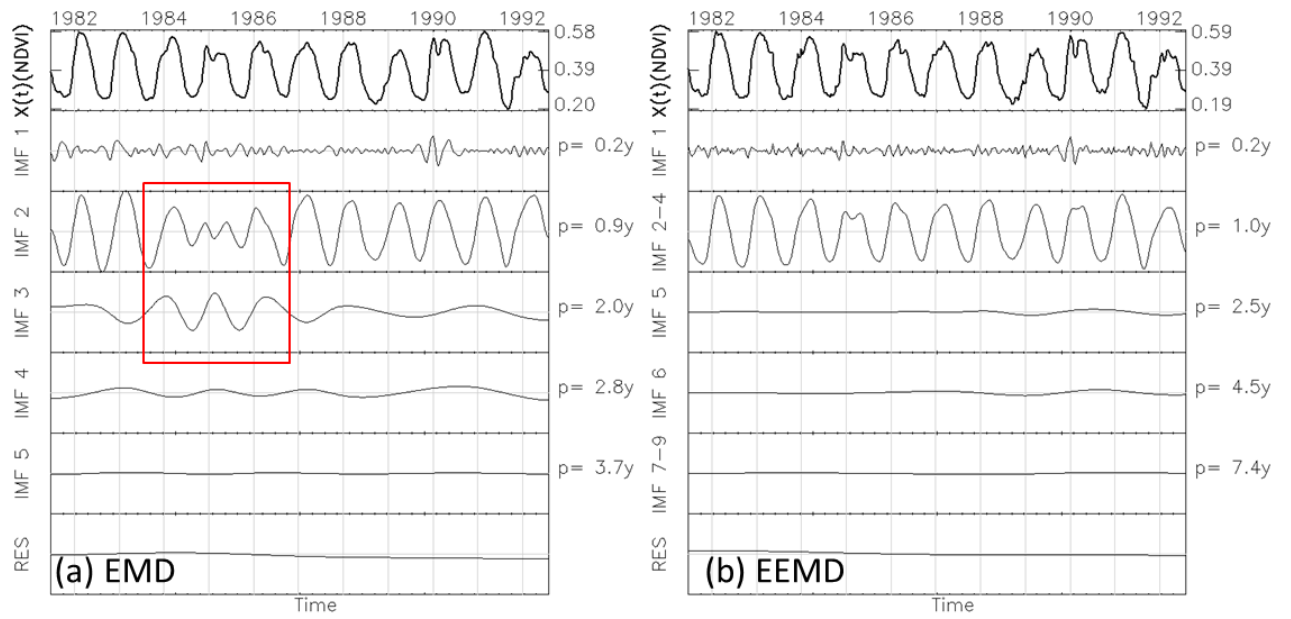


Figure 2. A temporal NDVI profile (pixel 7 in Figure 3, North Tanzania) and its Intrinsic Mode Functions by (a) EMD decomposition and (b) the improved EEMD decomposition. EEMD decreases ‘mode mixing’ whereby fragments of a single time scale occur in another component, e.g. for the annual time scale for the period 1984-1986 (box on graph (a)).

Although EEMD was applied recently by various authors (e.g., Feng et al. 2012; Guan 2014; Kuo et al. 2013; Zhou et al. 2014b), no formal definition of *corresponding* IMFs, required to sort them into ensembles, has been given. However, automated EEMD analysis of a large array of per-pixel NDVI time series requires a robust sorting procedure, certainly because different noise realizations can yield slightly different numbers of IMFs, and assigning each IMF to its appropriate group (or *bin*) before averaging is crucial in attaining successful mode separation. To formalize the IMF sorting step, we propose to use IMF periods  $p_i$  (i.e., the series length divided by twice the number of zero-crossings in  $\text{IMF}_i$ ) as the basic criterion, where the EMD decomposition of the original series without added noise defines reference periods  $p_{\text{ref},1}, \dots, p_{\text{ref},k}$ . Since EMD is found to produce components with a general pattern of doubling (or exponentially growing) periods (Flandrin et al.

2004; Wu and Huang 2004), the geometric means of subsequent reference periods  $p_{ref.j}$  are considered as the bin boundaries for assigning IMFs to a bin after each noise realization.

$$bin_j = [\sqrt{p_{ref.j-1}p_{ref.j}}, \sqrt{p_{ref.j}p_{ref.j+1}}] \quad (Eq.4)$$

The sorting algorithm thus evaluates the IMFs of each noise-distorted ensemble member, and assigns them to their proper pre-defined period bins. The IMFs in a bin are then averaged over the number of noise realizations  $N_n$ , to yield a decomposition with better mode separation. Our implementation uses parameter values for added noise amplitude [ $\sigma_{add} = 0.1$ ] as in other EEMD applications (Kuo et al. 2013; Wu and Huang 2009) and [ $N_n = 50$ ] since the slight differences in outcomes for higher  $N_n$  did not offset linearly increasing processing time.

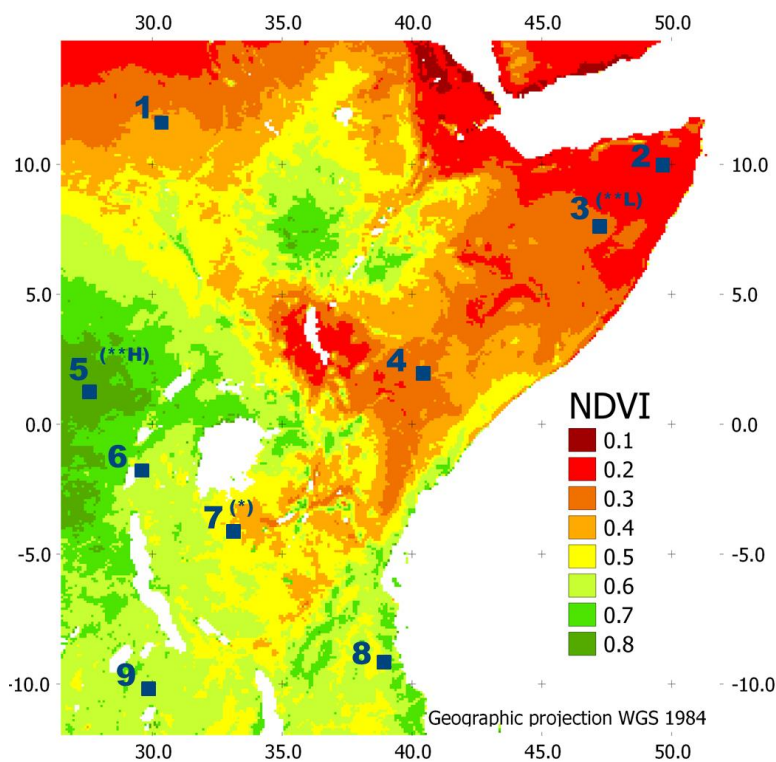
### 2.3. Simulated time series

Our central hypothesis is that observed NDVI time series are composed of an annual component encompassing one or two growing seasons, an interannual component including climatic influence as well as residual effects of sensor merging and orbital drift, and a high-frequent noise component reflecting residual sensor noise, radiometric and geometric errors (Lhermitte et al. 2011). Each of these components can be present in varying amplitude levels and under varying degrees of irregularity in timing. For the sensitivity analysis of the EEMD model's performance to be representative and the detection method to be generic, these forms of variability must be parameterized and the parameter ranges be estimated from a real NDVI dataset, here the intercalibrated AVHRR/VGT dataset described in Section 2.1.1.

#### 2.3.1. Study area stratification

Figure 3 shows the study area represented by each pixel's mean NDVI value ( $\mu_{tot}$ ) over the entire series, thereby revealing the major ecoregions in East and Central Africa. The series of 9 pixels with distinct NDVI levels and seasonal profiles were selected across climatic regions to

249 optimally explore parameter ranges related to NDVI data. Figure 4 depicts cross-calibrated temporal  
 250 NDVI profiles derived from the combined AVHRR and VGT datasets for this set of pixels.



251  
 252 *Figure 3. Mean NDVI value over the period 1981-2012 per image pixel over East and Central*  
 253 *Africa. The square symbols indicate the locations of the selected pixels, used to estimate parameters*  
 254 *for NDVI time series simulation (Table 1).*

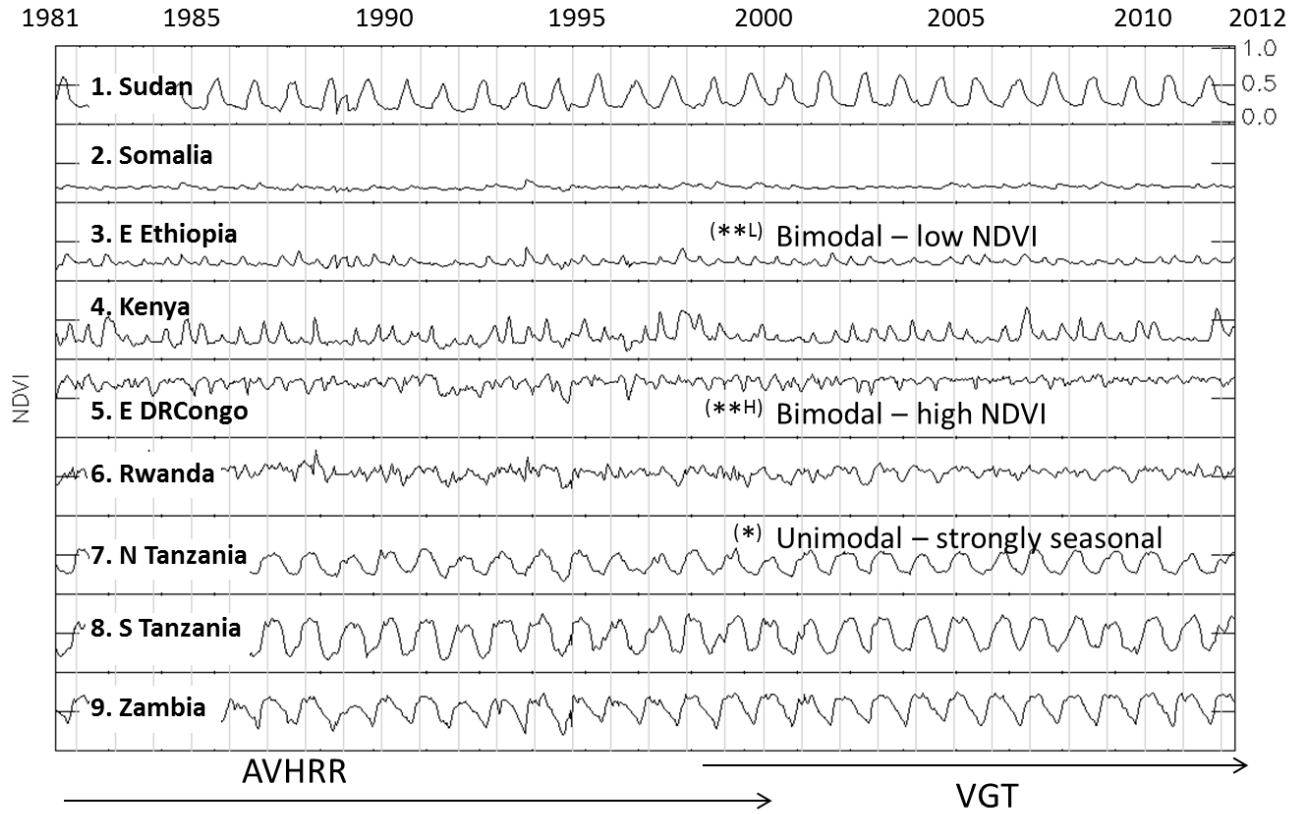


Figure 4. Time series of the Normalized Difference Vegetation Index (NDVI) for 9 pixels in distinct climate zones in East and Central Africa (Figure 3), derived from cross-calibrated image data from the NOAA-AVHRR (1981-1999) and SPOT-VGT (1998-2012) satellite sensors. Three prototypes of growing seasons were selected for data simulations: (\*)unimodal (one rainy season) and (\*\*)bimodal (two rainy seasons) with either overall low (L) or high (H) NDVI levels.

### 2.3.2. Estimation of variability in annual, interannual and noise components

Without any prior knowledge of relative signal amplitudes in real NDVI time series, a first estimate was made from their respective IMFs. The IMFs resulting from EEMD of each of the nine series were grouped into noise IMFs, annual IMFs and interannual IMFs, following the bin boundary logic as described in Section 2.2. Considering the occurrence of bimodal growing seasons, 0.5 year and 1 year are taken as the theoretical periods for annual cycles. As IMFs normally fall within period bins of doubling frequencies, the bin boundaries are set at  $0.5/\sqrt{2}$  years and  $1.0/\sqrt{2}$  years. Shorter

period IMFs are labeled as noise, whereas the sum of longer period IMFs is a first representation of the interannual component. The amplitude of each component is calculated as its standard deviation ( $\sigma$ ). Furthermore, mean NDVI values ( $\mu_{\text{tot}}$ ) and the numbers of modes in the average yearly growing season were tabulated per series (Table 1). Three prototypes of NDVI seasonality were identified for further modeling: a weak bimodal season with high NDVI <sup>(\*\*H)</sup> (humid conditions, e.g., East DR Congo), strongly seasonal unimodal season <sup>(\*)</sup> (subhumid conditions, e.g., North Tanzania), and an erratic bimodal season with low NDVI <sup>(\*\*L)</sup> (semi-arid conditions, e.g., East Ethiopia).

*Table 1. Estimated parameters for the time series of 9 selected pixels: amplitudes of noise ( $\sigma_{\text{noise}}$ ), annual ( $\sigma_{\text{ann}}$ ) and interannual ( $\sigma_{\text{int}}$ ) components, total amplitude ( $\sigma_{\text{tot}}$ ) and mean value ( $\mu_{\text{tot}}$ ) of the series, and the number of modes in the annual growing season. Three prototype seasons for further modelling are labeled as unimodal <sup>(\*)</sup> with strong seasonality and bimodal <sup>(\*\*)</sup> with low <sup>(L)</sup> and high <sup>(H)</sup> NDVI.*

<b>Location</b>	$\sigma_{\text{tot}}$	$\sigma_{\text{noise}}$	$\sigma_{\text{ann}}$	$\sigma_{\text{int}}$	$\sigma_{\text{int}}/\sigma_{\text{ann}}$	$\mu_{\text{tot}}$	# modes
1. Sudan	0.14	0.02	0.12	0.03	0.27	0.35	1
2. Somalia	0.02	0.01	0.01	0.02	1.09	0.20	2
3. E Ethiopia <sup>(**L)</sup>	0.04	0.02	0.03	0.02	0.66	0.24	2
4. Kenya	0.09	0.01	0.07	0.05	0.64	0.29	2
5. E DR Congo <sup>(**H)</sup>	0.06	0.03	0.04	0.03	0.74	0.70	2
6. Rwanda	0.07	0.03	0.04	0.03	0.69	0.54	2
7. N Tanzania <sup>(*)</sup>	0.10	0.01	0.10	0.02	0.19	0.39	1
8. S Tanzania	0.17	0.02	0.15	0.03	0.22	0.47	1
9. Zambia	0.12	0.03	0.11	0.03	0.23	0.53	1

### 2.3.3. Annual component

Growing seasons generally appear as peaks in NDVI time series, with a certain degree of irregularity. A flexible parametric model for a seasonal NDVI peak was adopted from Jönsson and Eklundh (2002). Its basic approach is to fit an asymmetric Gaussian model function  $f(t)$ , defined by its base level  $b$ , peak position  $p$  and amplitude  $A$ , and the width  $w_{l,r}$  and flatness  $f_{l,r}$  of both tails (see

Equations 5 and 6). This approach was expanded to the case of bimodal growing seasons which are modeled as two additive peaks with different peak locations within the year. A unimodal or bimodal peak was thus fitted to each of the 31 growing seasons of the three prototype series spanning 1981 to 2012. Sample means and standard deviations ( $n = 31$ ) give an account for the expected values and natural variation of the seasonal parameters throughout the study area (Table 2). These sample statistics were used to generate simulated annual components as a function of time  $f(t)$  with realistic shapes (base level, amplitude, peak widths and flatness) and controlled variation in irregularity (peak positions).

$$f(t) = b + A \cdot g(t) \quad (\text{Eq.5})$$

$$\text{with } g(t) = \begin{cases} \exp[-((t - p)/w_l)^{f_l}]; & \text{if } t > p \\ \exp[-((t - p)/w_r)^{f_r}]; & \text{if } t < p \end{cases} \quad (\text{Eq.6})$$

Table 2. Sample statistics from time series of 3 prototype growing seasons, denoted as mean (standard deviation). Five parameters represent the shape and timing of the first (I) and second (II) growing season: base level  $b$ , peak position  $p$  and amplitude  $A$ , and the width  $w_{l,r}$  and flatness  $f_{l,r}$  of the tails (as in Jönsson and Eklundh 2002; see Equations 5 and 6).

Seasonality type	b (NDVI)	A (NDVI)		p (years)		W <sub>l</sub> (years)		W <sub>r</sub> (years)		$f_l$		$f_r$	
		I	II	I	II	I	II	I	II	I	II	I	II
** <sup>L</sup> Bimodal (Low NDVI)	0.17 (0.04)	0.25 (0.09)	0.30 (0.10)	0.37 (0.03)	0.97 (0.04)	0.15 (0.12)	0.14 (0.11)	0.10 (0.03)	0.07 (0.05)	1.39 (0.85)	1.86 (1.50)	1.62 (0.62)	2.19 (1.78)
** <sup>H</sup> Bimodal (High NDVI)	0.61 (0.09)	0.21 (0.07)	0.19 (0.05)	0.38 (0.09)	0.83 (0.09)	0.30 (0.17)	0.23 (0.17)	0.15 (0.09)	0.17 (0.11)	2.32 (1.64)	2.88 (2.53)	2.16 (1.32)	2.46 (1.70)
* Unimodal (Strongly seasonal)	0.23 (0.03)	0.32 (0.05)	-	0.45 (0.10)	-	0.29 (0.10)	-	0.28 (0.09)	-	2.64 (1.42)	-	2.51 (1.10)	-

For each of the seasonality types, sequences of growing seasons were generated with their respective mean values of base level, amplitude and peak positions, widths and flatness. Seasonal irregularity ( $\varphi_{seas}$ ) was introduced by adding a random variation of 0.0, 0.5, 1.0 and 1.5 times the standard deviations for the respective peak positions.



#### 2.3.4. Interannual component

Realistic and representative a priori simulations of interannual variability are more difficult to obtain, since they are the outcome our tool aims to deliver. Therefore we combine descriptions found in literature on the impact of interannual climate variability on vegetation with our additive hypothesis and with the estimated levels of variability from the model series set of our study area. The major coupling between climatic variability and vegetation phenology is thought to act through episodes of severely increased or decreased precipitation (Holmgren et al. 2013). One well-known cause of such episodes is the El Niño Southern Oscillation (ENSO), a recurrent climate phenomenon at a 3 to 7-yearly time scale (IPCC 2007) which is known to force vegetation growth beyond its seasonal cycle (Holmgren et al. 2013). Although the interactions are complex in nature and region dependent (Sitters et al. 2012), increased precipitation episodes generally cause a rapid, but lasting response over several years (Holmgren et al. 2001).

Within the limitations of our additive model, we thus represent climate-driven interannual variability in NDVI as a weak modulation, with a steep increase and a relative slow decline. We employ again the asymmetric Gaussian simulation model to control the corresponding parameters. ENSO peak positions ( $t_{\text{ONI}}$ ) and peak-to-peak amplitude variations ( $A_{\text{ONI}}$ ) were derived from the historic ONI series, to reconstruct historic ENSO episodes and estimate the natural variability in duration of episodes ( $\mu_{t_{\text{ONI}}}$ ;  $\sigma_{t_{\text{ONI}}}$ ) for the simulation of irregular episodes with relative magnitudes ranging from 1 to 3 ( $R_{1-3}$ ). Table 3 lists the resulting set of interannual models. The overall interannual amplitude levels ( $A_{\text{int}}$ ) were defined as fractions of the annual amplitude ( $\sigma_{\text{int}}/\sigma_{\text{ann}}$ ), which were in turn estimated from the interannual IMFs obtained by EEMD decomposition of the NDVI model series set. Based on the range of estimated annual/interannual ratios in Table 1, this parameter takes on values 0.1, 0.2, 0.33, 0.5 and 1.0 in the simulations.

330 Table 3. Various models for interannual variability were based on the historic ONI index, defined by  
 331 the timing of its episodes ( $t_{ONI}$ ) and their amplitudes ( $A_{ONI}$ ) with optional random fluctuations at  
 332 three different levels  $R_{1-3}$ . The sample statistics of episode duration ( $\mu_{t.ONI}, \sigma_{t.ONI}$ ) are used to  
 333 model irregular episodes (I).

Label	Description	Parameters
$H_{oni}$	Historic Oceanic Niño Index	$(t_{ONI}, A_{ONI}) \rightarrow \mu_{t.ONI}, \sigma_{t.ONI}$
$H_{cst}$	Historic episodes, constant amplitude	$f(t_{ONI}, A_{int})$
$H_{var}$	Historic episodes, historic varying amplitude	$f(t_{ONI}, A_{int} * A_{ONI})$
$R_{cst}$	Regular episodes, constant amplitude	$f(\mu_{t.ONI}, A_{int})$
$R_{rnd}$	Regular episodes, random varying amplitude	$f(\mu_{t.ONI}, A_{int} * R_{1-3})$
$I_{cst}$	Irregular episodes, constant amplitude	$f(\mu_{t.ONI} + \sigma_{t.ONI}, A_{int})$
$I_{rnd}$	Irregular episodes, random varying amplitude	$f(\mu_{t.ONI} + \sigma_{t.ONI}, A_{int} * R_{1-3})$

334

### 335 2.3.5. Noise component

336 Real world NDVI noise levels ( $\sigma_{noise}$ ) were estimated as the root mean square (*rms*) amplitudes  
 337 of the sum of high frequency IMFs of each of the model set series (Table 1), as these IMFs are  
 338 assumed to contain nearly all noise fragments. In order to assess the sensitivity of EEMD  
 339 performance to noise in the input time series, we added random noise with *rms* amplitudes 0.00,  
 340 0.01, 0.02, 0.03 and 0.05 NDVI. The noise model present in real NDVI series is unknown a priori.  
 341 As Mann and Lees (1996) argue, geophysical phenomena display a certain degree of persistence of  
 342 random distortions, quantified as the noise lag-1 autocorrelation ( $AC_1$ ) or *redness*. Therefore we  
 343 employed both white noise ( $AC_1 = 0$ ) and red noise ( $AC_1 = \{0.25, 0.50\}$ ) simulations drawn from a  
 344 normal distribution.

345 The full set of simulated series was generated by adding each combination of annual, interannual  
 346 and noise component, varying over 3 seasonality types, 4 levels of seasonal irregularity ( $\varphi_{seas}$ ), 7  
 347 interannual models, 5 interannual to annual amplitude ratios ( $\sigma_{int}/\sigma_{ann}$ ), 3 noise models ( $AC_1$ ) and 5  
 348 noise levels ( $\sigma_{noise}$ ). Sensitivity of the method's performance to reconstruct interannual components

349 was not only tested for data-related variations, but also for a method-related parameter, as described  
350 in the next paragraph.

#### 351 2.4. Components post-processing

352 The general approach to reconstructing the interannual component from EEMD components is to  
353 add combinations of detected longer-than-annual components. Estimation of components' periods  
354 based on the number of zero-crossings was outlined above. A currently unresolved issue in the post-  
355 processing approach is the selection of *significant* interannual components. Three different  
356 approaches to selection have been evaluated through sensitivity analysis.

357 The need for component selection originates from the potential occurrence of low frequency  
358 components in the decomposition of random noise present in the data. As discovered by Flandrin *et*  
359 *al.* (2004) and further examined by Wu and Huang (2004), (E)EMD breaks down white noise into  
360 components of approximately doubling periods. However, the energy (squared amplitude) of a white  
361 noise (E)EMD component is shown to be related to its period, and constrained by theoretical  
362 confidence bounds (see Appendix B). Monte Carlo verification of this relationship and its confidence  
363 bounds deliver a framework to distinguish a real signal component from noise-induced components,  
364 by checking whether its energy exceeds with high confidence the expected energy of a noise  
365 component with the same period. This framework is proposed by Wu and Huang (2005) and has  
366 been adopted for climatological (E)EMD applications (e.g., Coughlin and Tung 2005). The  
367 signal/noise distinction is however entirely dependent on the quantification of the noise level in the  
368 series. An 'a priori' test considers the entire series as potential noise, while an 'a posteriori' test can  
369 be performed by estimating the noise level from the high-frequent (E)EMD components which,  
370 under the additive hypothesis, are purely noise-induced (Wu and Huang 2005). However, we argue  
371 that a given (E)EMD component may simultaneously contain signal information and noise  
372 information with similar periods. Therefore, exclusion as well as inclusion will introduce some error

373 in the reconstructed interannual component. In case of sufficiently signal-to-noise ratios in the data,  
 374 this balance may be in favor of retaining all detected components without significance test. We  
 375 therefore consider ‘no test’, ‘a priori’ test and ‘a posteriori’ test in the sensitivity analysis for the  
 376 reconstruction of interannual components from simulated NDVI time series.

## 377 2.5. Performance measures

378 Successful detection and reconstruction of interannual components from a mix of known input  
 379 components, and its sensitivity to data-related and model-related parameters must be expressed in  
 380 quantitative measures. We propose three different performance measures to highlight different types  
 381 of correspondence between two time series (Lhermitte et al. 2011), in this case the input  $I_t$  and  
 382 reconstructed output  $O_t$  interannual components.

383 Correlation  $r$  between two time series indicates whether the detected pulses are correctly  
 384 localized in time and have consistently the correct direction (positive or negative). It therefore  
 385 indicates if statements on the occurrence in time of positive and negative climatic episodes are  
 386 reliable.

$$387 \quad r = \sum_t (I_t - \bar{I})(O_t - \bar{O}) / \left[ \sqrt{\sum_t (I_t - \bar{I})^2} \sqrt{\sum_t (O_t - \bar{O})^2} \right] \quad (\text{Eq.7})$$

388 The relative root mean squared error ( $rRMSE$ ) between two series summarizes the *rms* deviations  
 389 between input and reconstructed components, relative to the interannual input component’s *rms*  
 390 amplitude. It indicates if statements on the magnitude of particular episodes are reliable.

$$391 \quad rRMSE = \sqrt{\sum_t (I_t - O_t)^2 / \sum_t I_t^2} \quad (\text{Eq.8})$$

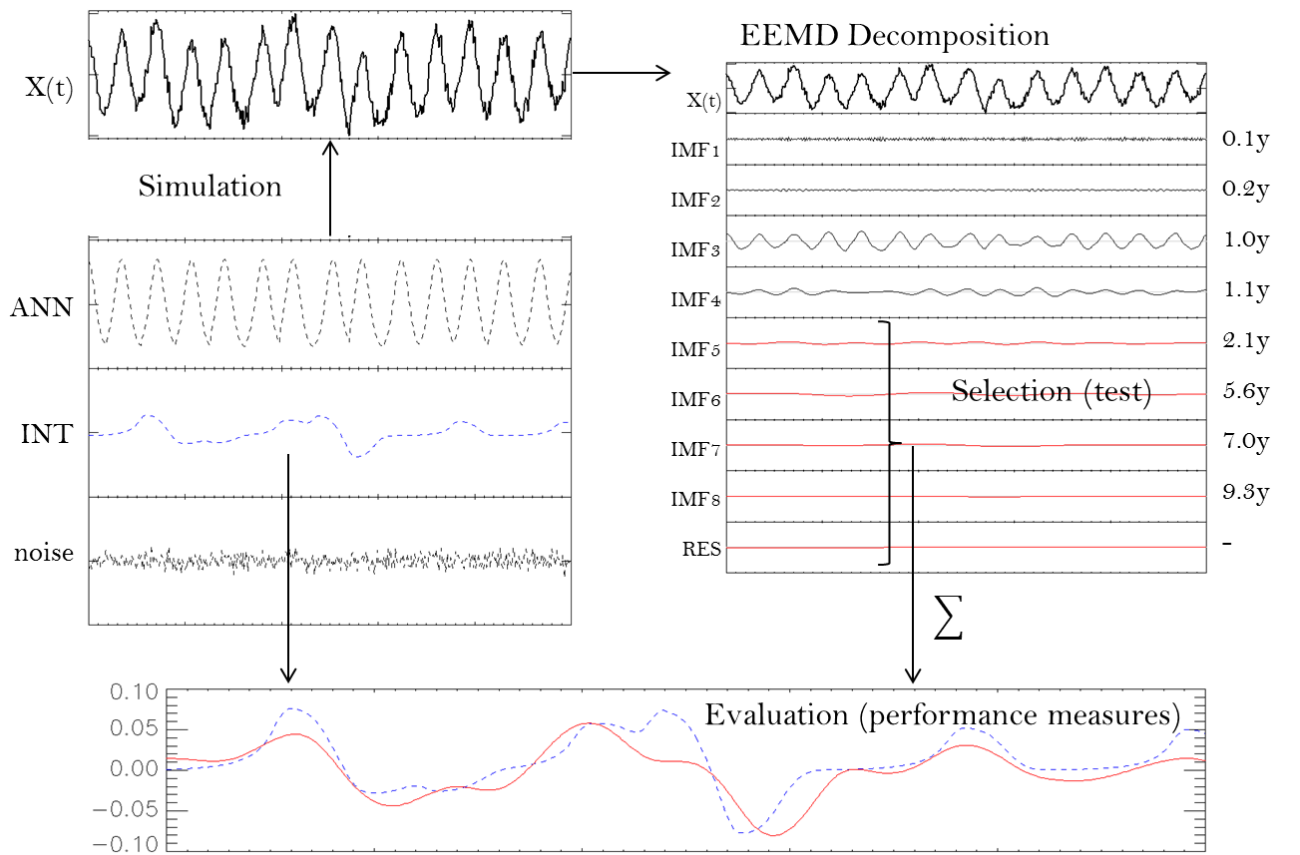
392 Finally, weighted spectral coherence ( $wCOH$ ) between two time series measures the  
 393 correspondence (from 0 to 1) of the spectral content of two time series  $X_t$  based on their Fourier  
 394 spectra  $F(X_t)$ , weighted by the Fourier spectrum of the reference series (with  $F^*$  the complex  
 395 conjugate of  $F$  and  $\langle . \rangle$  expectations estimated by ensemble averaging, see Alston et al. (2013) for a

396 detailed description). It therefore indicates the reliability of statements on the time scales of detected  
 397 oscillations.

$$398 \quad COH = |\langle F^*(I_t) \cdot F(O_t) \rangle|^2 / (\langle |F(I_t)|^2 \rangle \langle |F(O_t)|^2 \rangle) \quad (\text{Eq.9})$$

$$399 \quad wCOH = \sum (F(I_t) * COH) / \sum F(I_t) \quad (\text{Eq.10})$$

400 The overall strategy of composing a simulated series, its decomposition and subsequent  
 401 evaluation of the detected interannual component against the input component is illustrated in Figure  
 402 5.



403  
 404 *Figure 5. Overview of the evaluation framework. Mixtures  $X(t)$  of simulated annual (ANN),*  
 405 *interannual (INT) and noise components are decomposed using EEMD. The interannual component*  
 406 *(red solid line) is reconstructed from selected components and evaluated against the input*  
 407 *component (blue dashed line).*

## 408 2.6. Sensitivity analysis

409 Estimating sensitivity of the above described performance measures to the parameters in the  
 410 simulated series aims at identifying those factors which most affect the successful detection of  
 411 interannual components. Interannual to annual amplitude ( $\sigma_{\text{int}}/\sigma_{\text{ann}}$ ), seasonal irregularity ( $\varphi_{\text{seas}}$ ),  
 412 noise autocorrelation ( $AC_1$ ), noise level ( $\sigma_{\text{noise}}$ ), seasonality type (SEAS), interannual model (INT)  
 413 and reconstruction method (METH) each partially explain the variance in performance, which is  
 414 assessed through multiple linear regression. Real-valued variables ( $\sigma_{\text{int}}/\sigma_{\text{ann}}$ ,  $\varphi_{\text{seas}}$ ,  $AC_1$ ,  $\sigma_{\text{noise}}$ ) are  
 415 standardized with respect to their respective sample means and standard deviations, in order to make  
 416 the estimated regression coefficients comparable. Categorical variables (SEAS, INT, METH) enter  
 417 the regression equation as dummy variables. The regression coefficient for each category represents  
 418 the effect of the variable taking on that particular category with respect to a reference category,  
 419 enabling a ranking of categories per performance measure. Within the approximation that an increase  
 420 (decrease) of a real-valued variable by one standard deviation is equivalent to a categorical variable  
 421 taking on a different category, all estimated coefficients are intercomparable and the factors that most  
 422 affect the performance can be identified.

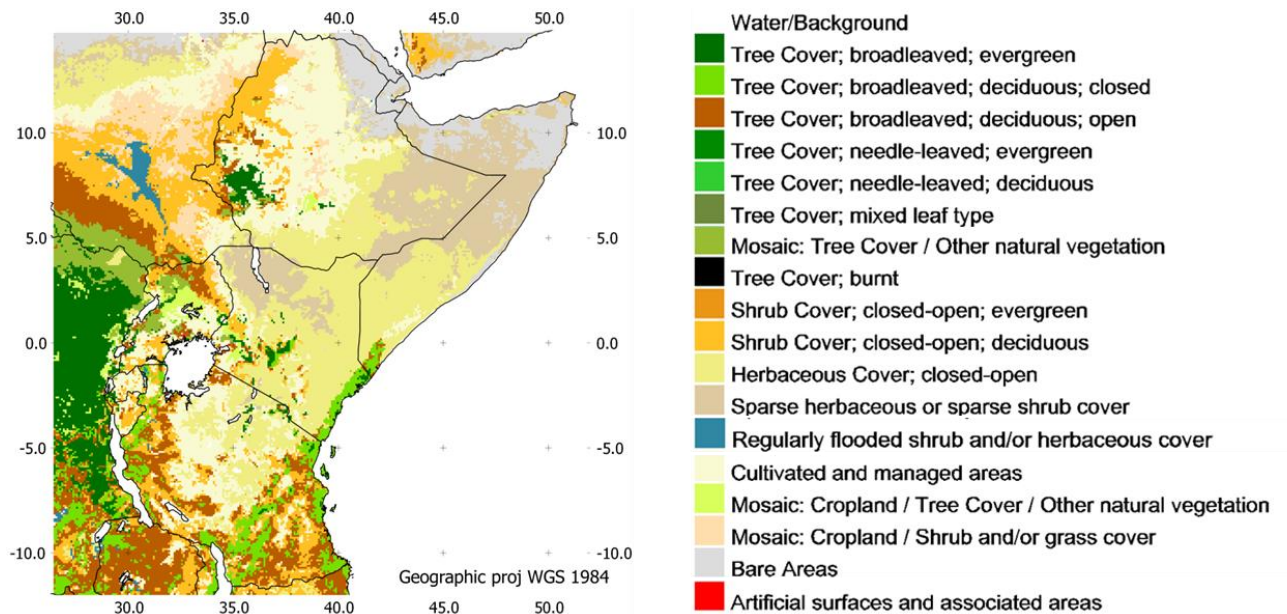
## 423 2.7. Case study: interannual NDVI and climate episodes

424 The validated performance of the EEMD method to retrieve interannual components from NDVI  
 425 time series is conditioned by the degree to which the simulated series are representative for real  
 426 world NDVI time series. To this end it was assessed in two steps whether the detected interannual  
 427 NDVI patterns over East and Central Africa correspond to the expected long term fluctuations as  
 428 predicted by historic climatic episodes.

429 In a first step, the zones where precipitation is most sensitive to interannual climatic and oceanic  
 430 forcing are mapped by correlating the one-year accumulated Standardized Precipitation Index (SPI)  
 431 with historic indices of two major climate phenomena acting in the region, i.e., ONI and DMI. The  
 432 SPI index is a z-score of a precipitation event compared to the historic sample of events in the same

433 period within the year, taking into account the non-normal distribution of rainfall events (Guttman  
 434 1999). The SPI algorithm allows the definition of a time scale, i.e., the width of the past time window  
 435 to consider as an accumulated precipitation event. SPI with a one-year time scale was used as a first  
 436 proxy of interannual precipitation. The resulting maps reveal where the climate phenomena described  
 437 by the indices have a strong coupling with the interannual precipitation patterns. This is where a  
 438 strong interannual NDVI response can be expected.

439 In a second step, the decomposition model is applied to the NDVI time series of each pixel in the  
 440 AVHRR/VGT dataset over East and Central Africa. The detected interannual components per pixel  
 441 (with the choice of model parameters guided by the outcomes of the sensitivity analysis) are in turn  
 442 correlated with the ONI and DMI indices. If EEMD detection on NDVI time series is effective, the  
 443 footprint of ONI and DMI must be found in the interannual vegetation changes in those areas  
 444 sensitive to precipitation fluctuations revealed in step one. A portion of the Global Land Cover map  
 445 (GLC2000; Bartholomé and Belward 2005) over the study area (Figure 6) assists in the interpretation  
 446 of the vegetation responses to climate variability.



447  
 448 *Figure 6. The distribution of land cover types over the study area (GLC2000; Bartholomé and*  
 449 *Belward 2005) reflects to a large extent the different levels of mean NDVI shown in Figure 3.*

Ecosystems respond differently to regional precipitation variability, as confirmed in the demonstration case study over East and Central Africa (see Discussion section).

452

### 3. Results

#### 3.1. Sensitivity and performance of EEMD interannual NDVI detection using simulated time series

Following the evaluation framework (Figure 5), the sensitivity of the EEMD method was assessed through multiple regression of the performance measures against data and model parameters.

459

Table 4. Multiple linear regression of 3 performance measures against data and model parameters indicates the sensitivities of the EEMD method. Real-valued variables are scaled in order to make their coefficients comparable to the dummy coefficients of categorical variables. Regression coefficients indicate the effect of a change of one standard deviation of a real-valued variable, or the effect of a change of category with respect to a reference category for categorical variables.

	Correlation		rRMSE		wCOH	
<i>Offset</i>	0.68	***	1.22	***	0.41	***
<i>Real-valued variables</i>						
$\sigma_{\text{int}}/\sigma_{\text{ann}}$	0.21	***	-0.41	***	0.21	***
$\varphi_{\text{seas}}$	-0.05	***	0.30	***	-0.08	***
$AC_1$	-0.08	***	-0.03	***	-0.06	***
$\sigma_{\text{noise}}$	-0.01	***	0.04	***	-0.02	***
<i>Categorical variables</i>						
SEAS (reference category = 'high bimodal')						
'low bimodal'	0.10	***	-0.42	***	0.12	***
'unimodal'	0.05	***	-0.20	***	0.12	***
INT (reference category = Hcst)						
Rcst	0.03	***	-0.07	***	0.08	***
Rrnd	0.00		0.02		0.05	***
Honi	0.03	***	-0.03		0.02	***
Icst	-0.02	**	0.03	.	-0.01	
Hvar	-0.02	***	0.02		-0.01	
Irnd	-0.04	***	0.02	***	-0.02	**
METH (reference category = 'no test')						
'a posteriori'	-0.16	***	0.05	***	-0.09	***



‘a priori’	-0.34	***	-0.00	-0.22	***						
P(X> t ) in Student-t:	0	***	0.001	**	0.01	*	0.05	,	0.1	,	1

465

466 Table 4 shows multiple linear regression coefficients of performance measures against  
467 parameters by least-squares estimation, along with their symbolized significance in a Student-t test.

468 Correlation between input and reconstructed output is primarily determined by the  
469 interannual/annual amplitude ratio ( $\sigma_{\text{int}}/\sigma_{\text{ann}}$ ) and to the choice of post-processing method, where  
470 both 'a priori' and 'a posteriori' testing tend to reduce the correlation between input and output  
471 interannual components relative to the no-IMF selection method ('no test'). To a lesser degree, more  
472 autocorrelation in the noise model tends to distort correlations, whereas the overall noise level has  
473 little impact over the range estimated from the real world dataset. While there is a limited  
474 discrepancy in input-output correlation between the different seasonal models and its degree of  
475 irregularity, the choice of interannual model does not affect correlation strongly.

476 The rRMSE between input and output interannual components takes on values in a range around  
477 unity. It decreases significantly only in the case of a strong interannual component, a relatively  
478 regular annual cycle, or a particular type of growing season. Noise characteristics, interannual  
479 models and selection criteria for interannual IMFs have less weight on the detection accuracy  
480 measured by rRMSE.

481 Weighted spectral coherence (wCOH) shows sensitivities very similar to that of correlation,  
482 favoring the inclusion of all detected interannual IMFs in the estimated interannual component.  
483 Again, the relative strength of the interannual component compared to the seasonal cycle is of more  
484 importance than their assumed underlying models or the characteristics of the noise in the series.

485 As a conclusion from the correlation, rRMSE and spectral coherence measures (Table 4) it can be  
486 seen that the 'no test' approach performs best to detect the input interannual components, but that the  
487 performance of this method is still strongly dependent on the interannual/annual amplitude ratio and  
488 seasonal irregularity expressed as a number of sample standard deviations in start of season. This can

be seen for example in Table 5, which contains the values of the performance measures as a function of these two data-related parameters, following the ‘no test’ approach.

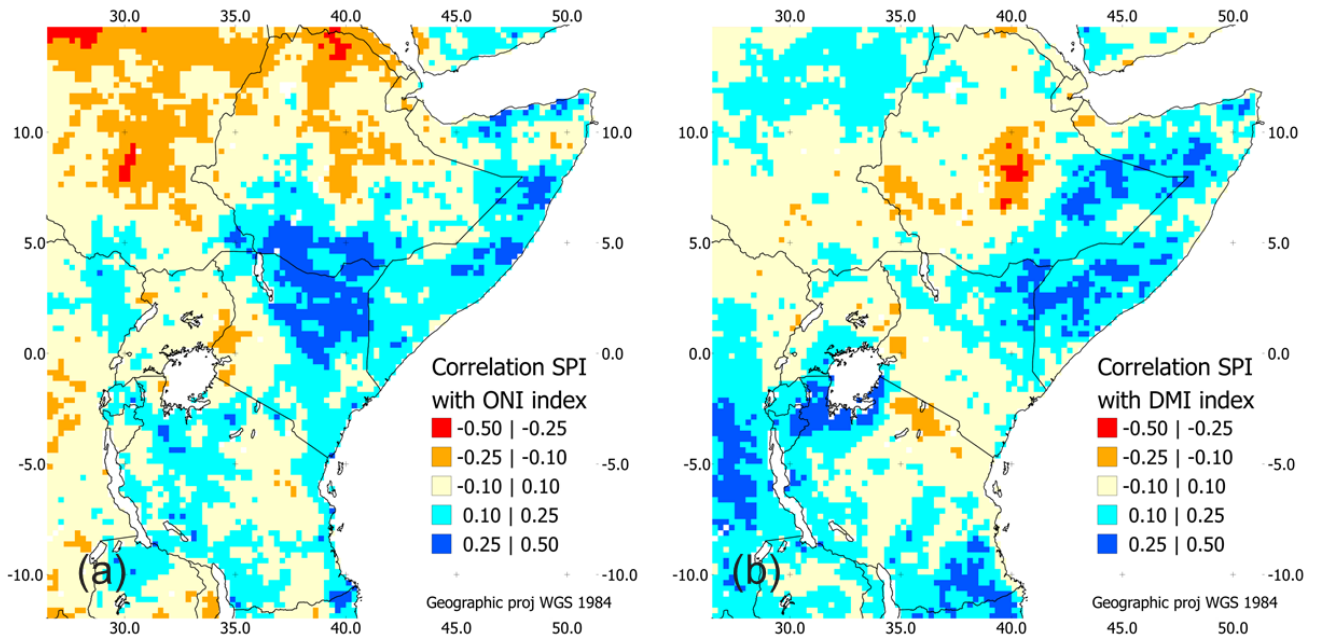
*Table 5. Performance measures of the ‘no test’ approach as a function of annual irregularity (ANN irr) and interannual/annual amplitude ratio (unimodal annual season, interannual model  $I_{\text{rnd}}$ , red noise ( $AC1 = 0.25$ ;  $\sigma = 0.03$  NDVI)). Darker shades indicate better detection performance.*

		Correlation				rRMSE				Weighted spectral coherence			
ANN irr ( $\sigma$ )		0.0	0.5	1.0	1.5	0.0	0.5	1.0	1.5	0.0	0.5	1.0	1.5
<i>INT/ANN ratio</i>	0.10	0.59	0.53	0.24	0.15	0.91	1.39	3.26	4.27	0.29	0.21	0.08	0.05
	0.20	0.86	0.70	0.41	0.49	0.54	0.76	1.69	1.36	0.65	0.28	0.15	0.23
	0.33	0.90	0.81	0.75	0.53	0.45	0.61	0.82	1.10	0.71	0.58	0.59	0.25
	0.50	0.91	0.88	0.82	0.65	0.45	0.49	0.66	0.90	0.70	0.70	0.55	0.31
	1.00	0.92	0.83	0.91	0.92	0.64	0.58	0.44	0.41	0.75	0.57	0.77	0.74

### 3.2. Case study over East and Central Africa

Figure 7 displays the correlation of precipitation patterns in East and Central Africa with dominant regional climate phenomena. The ONI index, representing the El Niño Southern Oscillation (ENSO) based on Pacific sea surface temperatures, explains a part of the precipitation variability principally in the regions most exposed to oceanic influence (Figure 7a). ENSO forcing is strongest in the Somalian, Ethiopian and Kenyan lowlands, only stretching further inland through the Turkana basin. Elsewhere its influence is limited by the Eastern and Southern rift mountains. Precipitation patterns in the Sudan lowlands towards the Sahel are rather out of phase with ENSO, pointing at the dominance of more local phenomena either not described by ENSO or negatively interfering with it (Williams and Hanan 2011). Plisnier et al. (2000) indicated that (a) the effect of global ENSO episodes is often overruled by local climate agents such as large lakes, (b) the Indian Ocean dynamics might provide a better proxy for climate variability in certain African regions. As seen from Figure 7b, The Indian Ocean DMI index, explains more variability of the Sahelian precipitation in the absence of direct ENSO influence. In addition, the precipitation downwind of

509 Lake Victoria and Lake Tanganyika responds more to DMI forcing, stretching as far as the tropical  
 510 rainforest in the Congo Basin (Figure 6).



511  
 512 *Figure 7. Spatial representations of the correlation between one-year accumulated SPI and indices*  
 513 *of regional climate phenomena highlight the areas where precipitation variability is sensitive to (a)*  
 514 *the El Niño Southern Oscillation and (b) the Indian Ocean Dipole Mode. Oceanic exposure and*  
 515 *local climate factors such as lakes partially predict sensitivity to these influences.*

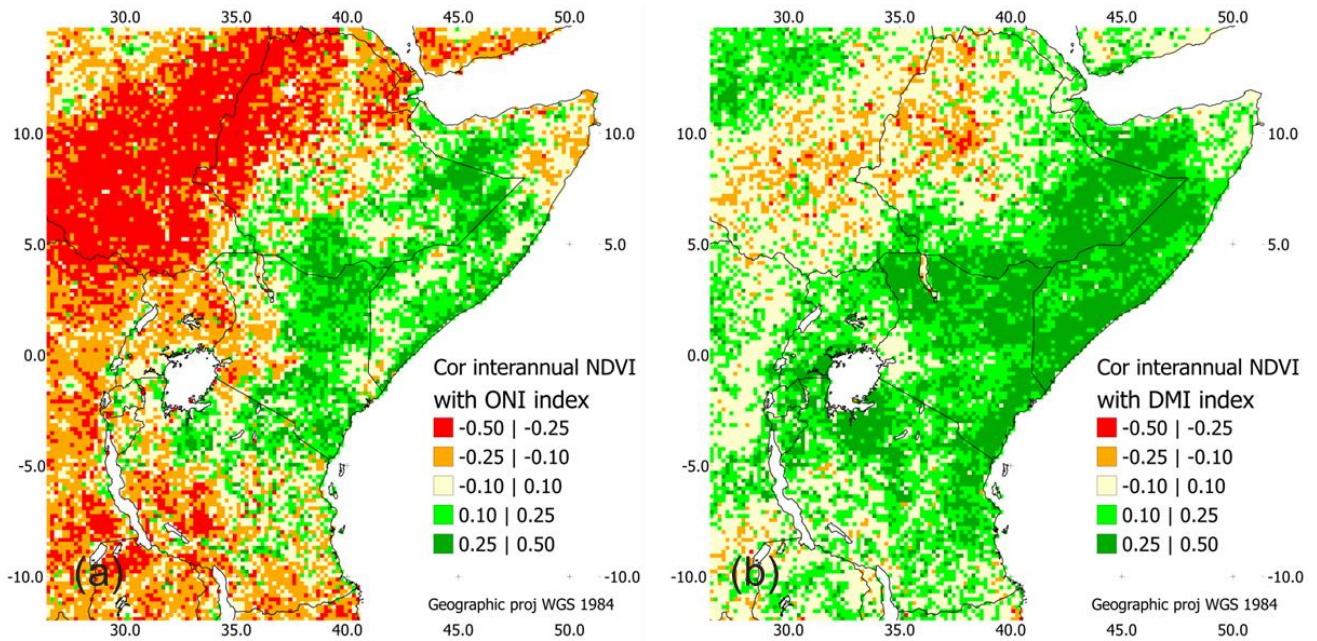


Figure 8. Correlation maps of EEMD detected interannual NDVI with the historic ONI and DMI indices highlight the areas where vegetation changes are influenced by regional climate variability. These areas largely correspond to the areas where precipitation is forced by the same regional oceanic phenomena, demonstrating that meaningful interannual NDVI components can be extracted using EEMD decomposition.

Next, it was assessed whether EEMD detected interannual NDVI is able to reveal the expected vegetation responses in the areas sensitive to climate variability. Figure 8 shows the strength of the coupling between interannual NDVI and the ONI and DMI indices respectively. The interannual NDVI follows the ONI index in most of the lowlands identified as sensitive to ENSO (Figure 8a), dominated by herbaceous and sparse shrub cover. However, the deciduous forest areas north of the Congo Basin do not respond to wet ENSO-driven episodes. As expected, vegetation in the continental lowlands responds negatively to lower than usual precipitation amounts during warm ENSO phases.

Correlation between interannual NDVI and DMI emphasize these findings. Although the Indian Ocean effects act differently throughout the study area, the detected responses of vegetation to DMI

532 episodes matches the areas identified as sensitive to DMI well in most areas. The ocean–exposed  
533 lowlands under low vegetation cover display greenness anomalies in response to increased  
534 precipitation during positive DMI episodes. The same holds for other DMI-sensitive areas in the  
535 Eastern Sahel and around Lake Victoria. Remarkably, the coupling of vegetation to the DMI  
536 episodes cannot be explained everywhere by its effect through precipitation, for example in vast  
537 areas of South Kenya and North Tanzania. Again, the forest ecosystems of the Congo Basin are  
538 neutral towards precipitation variability driven by Indian Ocean phenomena. A similar observation is  
539 made for the partly forested areas in South Tanzania: despite strongly DMI-forced precipitation, the  
540 NDVI response is rather ambiguous. Finally, the out of phase character of precipitation in the  
541 Ethiopian highlands with respect to DMI is also detected in the interannual NDVI.

542 The lower response of tropical forest ecosystems reflects the lower importance of water as a  
543 limiting factor, as well as the saturation effect of NDVI for high leaf area canopies (Sellers 1985). In  
544 addition, forest-climate interactions (Makarieva and Gorshkov 2007) and moisture recycling  
545 dynamics (van der Ent et al. 2010) are known to cause particular rainfall dynamics above forests,  
546 partly independent from the dominant oceanic moisture supply.

547

#### 548 **4. Discussion**

549 Ensemble Empirical Mode Decomposition (EEMD) proves to be a suitable algorithm for the  
550 automated decomposition of large sets of NDVI time series into their characteristic time scales. The  
551 original EEMD decomposition technique (Huang et al. 1998; Wu and Huang 2009), complemented  
552 by the IMF sorting procedure proposed in §2.2 and clear choices of parameters for *sifting* and  
553 *splining* (Appendix A), is able to deliver the interannual components of any given time series.

554 With respect to reconstructing the interannual component from detected components, we reject  
555 the existing significance test to distinguish signal from noise-induced components for interannual

556 component detection, since neither the ‘a priori’ or ‘a posteriori’ version of the test yield better  
557 results than the ‘no test’ approach. Instead we weighted the capabilities of these significance tests to  
558 identify noise-induced low frequency components against the risk that these components may in fact  
559 contain signal as well as noise fragments (hereafter called *mixed* components). Although neither  
560 approach ensures a precise reconstruction of interannual components in terms of rRMSE, the linear  
561 and spectral properties of such components were best recovered by retaining all interannual IMFs  
562 (‘no test’). This implies that mixed components, if occurring in the decompositions of our simulated  
563 time series, contain on average more signal than noise fragments. Attempts to filter noise-affected  
564 components by subjecting individual IMFs to significance tests decreased performance measured by  
565 correlation and spectral coherence.

566       However, two nuances must be added to this finding. First, it may hold true for the tested ranges  
567 of  $\sigma_{\text{int}}/\sigma_{\text{ann}}$  and absolute  $\sigma_{\text{noise}}$ , which were in turn based on estimated ranges from a real NDVI  
568 dataset. Outside these ranges noise may start to dominate low frequency EEMD components,  
569 prompting a significance test to retain the true signal components. This may be commonly the case  
570 for other biogeophysical or climatological datasets and applications, so our conclusion should be  
571 limited to the application on integrated time series of remotely sensed vegetation indices and its  
572 typical signal to noise ratios. Second, it can be argued that the purpose of IMF significance testing in  
573 a climatological context, as in the work of Coughlin and Tung (2005), is to isolate *pure* time scales  
574 with a high degree of probability to originate from signal rather than noise. This justifies strict  
575 filtering of potentially noise-induced IMFs. Conversely, when using multiple IMFs to reconstruct  
576 interannual components with an unknown combination of time scales, retaining both *pure* and *mixed*  
577 IMFs may be favorable as a strategy.

578       The values of the performance measures for given (inter)annual models and noise characteristics  
579 under the ‘no test’ approach (Table 5) give an account of the major sources of variability in  
580 performance, i.e., the relative strength of the interannual component compared to the dominant

581 annual cycle ( $\sigma_{int}/\sigma_{ann}$ ), and the irregularity in timing of the annual season ( $\varphi_{seas}$ ). It is worth noting  
 582 that both factors do not act independently. The distorting effect of irregular growing seasons is of  
 583 less impact when the superimposed interannual modulation is sufficiently high in amplitude, for  
 584 example in arid ecoregions with a strong oceanic influence (Figure 6). A practical implication is that  
 585 both factors must preferably be estimated upon detection. Low  $\sigma_{int}/\sigma_{ann}$  ratios, corresponding to  
 586 weak interannual changes compared to the NDVI range of the growing season, may hamper the  
 587 detection and subsequent processing of a pixel's interannual component, unless the annual cycle  
 588 displays a sufficiently regular timing. If threshold values for both parameters are considered, pixels  
 589 can be masked out from further interpretation. Whereas the choice of thresholds is arbitrary and  
 590 dependent on the further steps in a particular application, the results presented in Table 5 offer some  
 591 guidelines. For example, a threshold of  $[\sigma_{int}/\sigma_{ann} > 0.33]$  will generally ensure a good  
 592 reproduction of the interannual component measured by correlation and spectral coherence. As seen  
 593 from Table 1, this applies for all ecoregions with a dry or wet bimodal growing season. For unimodal  
 594 (semi-arid to subhumid) ecoregions, the interannual NDVI components are buried under a more  
 595 dominant seasonal component. However, if the estimated variability (measured as standard  
 596 deviation) of the growing season peak position does not exceed half of the sample standard deviation  
 597 used in our simulated prototype (0.10 years, see Table 2), then the performance level is largely  
 598 maintained. We therefore recommend that automated use of EEMD to reveal interannual components  
 599 from large gridded time series data (biogeophysical, climatological) be preceded by a calibration  
 600 step, whereby preliminary estimates of the series' composition and characteristics are collected in  
 601 order to assess the proper limits of detection.

602 A major implication for the further use of detected interannual components of NDVI (or other  
 603 remotely sensed vegetation indices) in a causal analysis with gridded climate datasets, is the fact that  
 604 detection performs relatively well when measured by correlation or spectral coherence, but proves  
 605 imprecise with respect to its rRMSE deviation from the true component. This suggests that positive

606 and negative episodes in interannual vegetation change can be localized, and that the time scales  
607 present in the series are represented well. Conversely, the high rRMSE values ( $\sim 0.40$  under optimal  
608 conditions) indicate that an EEMD detected interannual component of a time series does not  
609 necessarily represent the actual interannual NDVI change at each discrete point in time. Neither can  
610 the absolute amplitudes of individual positive or negative episodes be interpreted as such. The power  
611 of the decomposition tool lies in the capability to filter the desired time scales from a mixed signal,  
612 and to produce a global representation of the occurrence and relative intensities of positive and  
613 negative episodes. Further development of a technique to identify and isolate a climate-forced  
614 component in the interannual NDVI component must take this knowledge into account. It must not  
615 rely entirely on instantaneous responses in the time domain, but rather consider sufficiently large  
616 time windows as well as the spectral domain for bivariate analysis with climate series.

617 A first effort to shift the EEMD analysis beyond the simulated setting towards real world NDVI  
618 series demonstrated that spatially coherent patterns of vegetation dynamics can be revealed and  
619 explained (partially) by episodes of regional climate oscillations. Gridded precipitation datasets -  
620 remotely sensed as well as modeled using observational data - are expected to explain the detected  
621 interannual vegetation dynamics at a more local scale. Eventually, explained interannual variability  
622 can be separated from non-explained patterns, for further interpretative analysis over particular study  
623 areas.

624 The case study on real NDVI and climate datasets over East and Central Africa demonstrates that  
625 EEMD detection is able to produce meaningful indicators of interannual NDVI changes, as their  
626 spatial distribution corresponds largely to what can be expected from empirical climate data. As for  
627 any processing tool, the quality and the real world value of the output are inevitably limited by the  
628 quality of the input data. In the case of the EEMD decomposition of NDVI time series,  
629 inconsistencies in long term NDVI archives are the principal source of spurious patterns in the  
630 detected interannual NDVI, which may jeopardize conclusions in thematic studies like the case study



in this paper. The most likely causes of inconsistency can be categorized as within-sensor inconsistencies (e.g., orbital drift or imperfect corrections for it) or between-sensor inconsistencies (e.g., historic processing differences, imperfect intercalibration of spectral response, or differences in sun-target-sensor geometry). Other sources of error with a less systematic occurrence, such as sensor noise and undetected clouds, will have less effect on the detected outcome, as the EEMD technique efficiently isolates high frequent components. With this knowledge, the quantitative validation of the detection tool was based on simulated data rather than on any existing real world dataset containing residual inconsistencies. The LTDR/VGT dataset contains at least two potential sources of inconsistency. The first one is the empirical linear sensor intercalibration between AVHRR and VGT as described in Section 2.1.1 yields slightly biased residuals for NDVI values above 0.65. In practice, this may cause an upward jump in NDVI at the 1999 breakpoint for pixels in densely forested areas. Moreover, 1999 may not be representative for the full NDVI record in case of residual between-sensor inconsistency in the LTDR version 2 data, which may cause an artifact interfering with the former effect. The second source of inconsistency stems from between-sensor inconsistency of the VGT-1 and VGT-2 sensors related to spectral response discrepancies. This effect has been identified to cause an upward break in 2003 throughout all NDVI strata (Tian et al. 2015). For future applications, alternative datasets can be considered. The LTDR version 4 provides improvement upon the earlier version with respect to geolocation as well as an extension in time with successor NOAA platforms (NASA 2014). The updated 15-day composite NDVI product of the Global Inventory Modelling and Mapping Studies (GIMMS3g) results from efforts to recalibrate historic NOAA-AVHRR data by correcting for effects introducing spurious NDVI trends such as orbital drift and volcanic eruptions (Fensholt and Proud 2012; Pinzon et al. 2005). GIMMS3g is thus likely to display improved stability over time, although potential artefacts have been identified over various NDVI strata (Tian et al. 2015). Finally, the MODIS instruments have provided NDVI records from 1999 onwards, considered an improvement upon the AVHRR products due to their narrow band

656 definitions and wide dynamic range (Huete et al. 2002). Although generally deemed the alternative  
657 dataset with highest consistency, the MODIS NDVI series was found to contain the effects of sensor  
658 degradation (Wang et al. 2012).

659       Regardless the eventual choice of dataset, the EEMD decomposition and reconstruction approach  
660 in its current form is deemed operational to conduct thematic follow-up research. It is  
661 complementary to existing time series processing tools in the sense that ‘interannual NDVI’  
662 representing slow year-to-year evolution of vegetation greenness is a new key variable in remote  
663 sensing-driven environmental research. Its user community may invoke extraction tools according to  
664 their specific needs: BFAST (Verbesselt et al. 2010) for the detection of stepwise trends and  
665 breakpoints relating to abrupt and gradual vegetation disturbances, such as wildfires and recovery;  
666 TIMESAT (Jönsson and Eklundh 2002) for a detailed parameterization and quantification of  
667 parameters related to the growing season; SPIRITS (Eerens et al. 2014) for near-real time  
668 agricultural monitoring through processing of images and the extraction of vegetation indices related  
669 to crop status. EEMD is proposed to complement this list of tools as one to extract interannual  
670 vegetation changes in response to climatic oscillations and other sources of periodic disturbance  
671 episodes.

672       Despite this applicability, some points for methodological improvement can be defined. A review  
673 of existing methods to estimate a priori the nature and the level of noise from an NDVI time series  
674 may contribute to the calibration phase necessary before EEMD application on a new dataset. If  
675 noise can be modeled and estimated more accurately, the performance of the ‘a posteriori’  
676 significance test for IMFs may surpass that of the current ‘no test’ approach. Further refinement of  
677 the EEMD application for automated analysis of gridded time series data can consist of evaluating  
678 the effects of series length and temporal resolution, which were held constant at 1114 ten-day time  
679 steps in this analysis.

680

## 681 5. Conclusions

682 Available archives of more than thirty years of remotely sensed optical imagery provide large  
683 spatiotemporal datasets, showing changes in condition of terrestrial vegetation as per-pixel NDVI  
684 trajectories. Beside seasonal variation, weaker but considerable interannual fluctuations exist in the  
685 NDVI series, and their identification is of high interest for research aiming at quantifying the long-  
686 term effects of climate variability on ecosystems. Thereto, signal processing techniques can be  
687 employed to detect interannual NDVI components within quantified limits of uncertainty.

688 We found that the Ensemble Empirical Mode Decomposition (EEMD) technique, extended with  
689 a sorting procedure for IMF components, is suitable to split a given NDVI time series into its  
690 constituent components with distinct time scales. The longer-than-annual EEMD components can be  
691 combined to reproduce the overall interannual oscillation present within the series. Implementation  
692 for automated processing of large NDVI datasets requires some complementary algorithmic  
693 formalization, which we proposed in this paper.

694 In order to gain insights in the performance of this method to accurately represent the true  
695 interannual component, and its sensitivities to data and model parameters, we tested its performance  
696 in a controlled setting with simulated NDVI time series. With respect to performance, we concluded  
697 that EEMD-detected interannual components generally represent well the occurrence of positive and  
698 negative episodes with proper time scales, whereas the local amplitudes must not be interpreted for  
699 individual episodes. This finding provides useful insights for subsequent bivariate analysis of  
700 interannual NDVI with precipitation series. With respect to sensitivities, the strength of the  
701 interannual component relative to the seasonal cycle, and modality and timing of the growing  
702 seasons, proved to be the principal factors affecting the detection performance. In addition, they  
703 interact and should therefore be assessed upon detection so that time series with low confidence in  
704 detection outcome can be excluded from the analysis.

705 The effectiveness of the EEMD decomposition method to detect interannual vegetation was  
706 demonstrated on real NDVI and climate data over East and Central Africa. In most areas where  
707 precipitation variability is sensitive to regional climatic and oceanic forcing, the method reveals  
708 interannual vegetation changes that show the expected responses, except in dense forest ecosystems.  
709 Finally, some methodological points of action were defined for further development of this tool to  
710 extract environmentally relevant information from growing remote sensing data sources.

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962

#### 963 **Appendix A. The Empirical Mode Decomposition algorithm (Huang et al. 1998)**

964 A series  $X(t)$  is decomposed into a finite number of Intrinsic Mode Functions (IMFs) and a  
965 residual term  $R(t)$  following the additive model (Eq.3).

966 The locations and values of all local minima and maxima in a series  $X(t)$  are detected using an  
967 extrema-finding function. Endpoints of the series are not considered as extrema unless they lie  
968 outside the range defined by the nearest minimum and maximum. For flat sections, the (left) middle  
969 location is returned.

970 The lower (upper) envelope of  $X(t)$  is obtained by connecting the local minima (maxima) of  $X(t)$   
971 using a cubic spline. Cubic splines are uniquely defined when values for the second derivatives at the  
972 endpoints are provided. We follow the two-step approach of Pegram *et al.* (2008), here described for  
973 the left end of the lower (upper) envelope. The first original minimum (maximum) is mirrored  
974 around the left endpoint, and assigned the same second derivative. A cubic spline is calculated



975 through the minima (maxima), ignoring the left endpoint. If the left endpoint is found to lie outside  
976 the calculated envelopes, it is added to the extrema set and the spline is recalculated. This is to avoid  
977 splines to vary freely at the ends, which would cause end effects propagating through the following  
978 iterative sifting procedure.

979 The mean of lower and upper envelopes  $M(t)$  contains the low-frequency information of  $X(t)$ . The  
980 first ProtoMode Function ( $PMF_1$ ) of  $X(t)$  is obtained by subtracting  $M(t)$  from  $X(t)$ . This step is  
981 termed ‘sifting’ and  $PMF_1$  is enriched in high frequency information. Sifting  $PMF_1$  yields  $PMF_2$  and  
982 the procedure is repeated  $k$  times until the number of extrema and the number of zero-crossings have  
983 not changed for  $S$  consecutive siftings.  $PMF_k$  is taken as the first Intrinsic Mode Function ( $IMF_1$ ) of  
984  $X(t)$ . We follow the guidelines by Huang *et al.* (2003) and use  $[S = 5]$  as a stopping criterion for the  
985 sifting process.

986 The difference of  $X(t)$  and  $IMF_1$  is the (preliminary) residual. It is ingested in the sifting  
987 procedure to yield  $IMF_2$ , which will contain the high frequency information after subtraction of  
988  $IMF_1$ . More IMFs are obtained iteratively with increasing frequencies, until the (final) residual  $R(t)$   
989 is monotonic or has one extremum. It can be regarded as the residual trend in the series.

990 The computing cost of the EMD algorithm increases quadratically with the length  $N_t$  of the time  
991 series. Its most costly step is the cubic spline interpolation, which involves manipulations on  $N_t \times N_t$   
992 matrices. For  $N_t = 1114$ , the spline interpolation accounts for nearly 80% of the total computing  
993 cost of 1163 msec. In our IDL implementation, the computing time  $t_{comp}$  (in msec) for one series of  
994 length  $N_t$  is on average given by

$$995 \quad t_{comp} = (0.000858 * N_t^2 + 0.282 * N_t + 23.2) \quad (\text{Eq.A1})$$

996 For the EEMD extension, there is an additional linear increase with the number of noise-added  
997 iterations (set to 50 in this study). The vast number of pixels in a spatio-temporal dataset as the image

sets over East and Central Africa (>14000 land pixels at 20 km resolution) further pushes the total processing time into the order of magnitude of weeks.

## Appendix B. Significance test for IMFs based on period-energy relationships of white noise

The theoretical and derived empirical relationships to distinguish signal from noise, are based on two key characteristics of an IMF of a series with length  $N_t$ : its energy density

$$E = \frac{1}{N_t} \sum IMF^2 \quad (\text{Eq.B1})$$

and its theoretical mean period  $T$ , estimated as  $\hat{T}$  by counting the number of extrema divided by twice the series length. Wu and Huang derived that the energy of a population of white noise series normalized to unit energy density has a mean  $\bar{E}$ , related to its mean period  $T$ :

$$\ln(\bar{E}) = -\ln(T) \quad (\text{Eq.B2})$$

Moreover, the probability distribution of the energy density of a white noise IMF can be derived from the finding that  $N_t * E$  follows a  $\chi^2$ -distribution with  $N_t * E$  degrees of freedom:

$$p(N_t * E) = (N_t * E)^{N_t \bar{E}/2 - 1} \exp\left(-\frac{N_t * E}{2}\right) / (2^{N_t \bar{E}/2} \Gamma(N_t * \bar{E}/2)) \quad (\text{Eq.B3})$$

Through log-transformation of the energy density

$$y = \ln(E) \quad (\text{Eq.B4})$$

and substitution of Equations B2 and B4 into the probability distribution of Equation B3, the confidence levels for the log-energy density of an IMF originating from white noise can be estimated from its mean period  $\hat{T}$ .

$$p(y) = (N_t * \exp(y))^{N_t/(2\hat{T})} \exp(-N_t * \exp(y)/2) / (2^{N_t/(2\hat{T})} \Gamma(N_t/(2\hat{T}))) \quad (\text{Eq. B5})$$

The bias in the estimation of  $\hat{T}$  affects Equation B2 but preserves its linear relationship. Monte Carlo verification by a large number of random white noise simulations yielded the empirical relationship for series length  $[N_t = 1114]$ :

$$\ln(\bar{E}) = -1.08 \ln(T) + 0.12 \quad (\text{Eq.B6})$$

1021       The energy distributions and confidence levels were recalculated accordingly, and verified with  
1022 the simulation result. The (shifted) theoretical 99% confidence limit proved to bound 95% of the  
1023 white noise simulations. Similar outcomes with slightly different coefficients were found for red  
1024 noise simulations with  $[AC1 = \{0.25, 0.50\}]$ .

1025       As white noise is assumed to contain no information, real signal components will display  
1026 energies higher than can be expected from white noise with a chosen level of confidence. Under the  
1027 ‘a priori’ approach, a given time series consisting of signal and noise is normalized to unit energy  
1028 density and treated as being potentially pure noise. If however the noise level in the series can be  
1029 estimated, the normalization step can be performed more accurately ‘a posteriori’ and more signal  
1030 components can be distinguished. Both approaches were evaluated in this paper.

1032 **List of Figure Captions**

1033

1034 Figure 1. The Oceanic Niño Index (ONI) and the Dipole Mode Index (DMI) are derived from sea  
1035 temperature measurements and represent the positive and negative episodes of climate oscillations  
1036 that affect interannual rainfall patterns over East and Central Africa (IPCC 2007).

1037

1038 Figure 2. A temporal NDVI profile (pixel 7 in Figure 3, North Tanzania) and its Intrinsic Mode  
1039 Functions by (a) EMD decomposition and (b) the improved EEMD decomposition. EEMD decreases  
1040 ‘mode mixing’ whereby fragments of a single time scale occur in another component, e.g. for the  
1041 annual time scale for the period 1984-1986 (box on graph (a)).

1042

1043 Figure 3. Mean NDVI value over the period 1981-2012 per image pixel over East and Central  
1044 Africa. The square symbols indicate the locations of the selected series pixels(Figure 1), used to  
1045 estimate parameters for NDVI time series simulation (Table 1).

1046

1047 Figure 4. Time series of the Normalized Difference Vegetation Index (NDVI) for 9 pixels in  
1048 distinct climate zones in East and Central Africa (Figure 3), derived from cross-calibrated image data  
1049 from the NOAA-AVHRR (1981-1999) and SPOT-VGT (1998-2012) satellite sensors. Three  
1050 prototypes of growing seasons were selected for data simulations: (\*)unimodal (one rainy season)  
1051 and (\*\*)bimodal (two rainy seasons) with either overall low (L) or high (H) NDVI levels.

1052

1053 Figure 5. Overview of the evaluation framework. Mixtures  $X(t)$  of simulated annual (ANN),  
1054 interannual (INT) and noise components are decomposed using EEMD. The interannual component

(red solid line) is reconstructed from selected components and evaluated against the input component (blue dashed line).

Figure 6. The distribution of land cover types over the study area (GLC2000; Bartholomé and Belward 2005) reflects to a large extent the different levels of mean NDVI shown in Figure 3. Ecosystems respond differently to regional precipitation variability, as confirmed in the demonstration case study over East and Central Africa (see Discussion section).

Figure 7. Spatial representations of the correlation between one-year accumulated SPI and indices of regional climate phenomena highlight the areas where precipitation variability is sensitive to (a) the El Niño Southern Oscillation and (b) the Indian Ocean Dipole Mode. Oceanic exposure and local climate factors such as lakes partially predict sensitivity to these influences.

Figure 8. Correlation maps of EEMD detected interannual NDVI with the historic ONI and DMI indices highlight the areas where vegetation changes are influenced by regional climate variability. These areas largely correspond to the areas where precipitation is forced by the same regional oceanic phenomena, demonstrating that meaningful interannual NDVI components can be extracted using EEMD decomposition.